

**Mech 1.**

- a) Conservation of Mechanical Energy:

$$\Delta U = KE$$

$$m_1gL = \frac{1}{2}m_1v_1^2$$

$$v_1 = \sqrt{2gL}$$

- b) Newton's Second Law:

$$\sum F_y = ma$$

$$T - m_1g = m_1 \frac{v_1^2}{L}$$

$$T - m_1g = m_1 \frac{2gL}{L}$$

$$T = 3mg$$

- c) Conservation of Linear Momentum:

$$P_1 = P_2$$

$$m_1v_1 = (m_1 + m_2)v_2$$

$$m_1\sqrt{2gL} = (m_1 + m_2)v_2$$

$$v_2 = \frac{m_1}{m_1 + m_2}\sqrt{2gL}$$

d)

$$KE_1 = \frac{1}{2}m_1v_1^2 = m_1gL$$

$$KE_2 = \frac{1}{2}(m_1 + m_2)v_2^2 = \frac{m_1 + m_2}{2} \frac{m_1^2 2gL}{(m_1 + m_2)^2} = \frac{m_1^2 gL}{m_1 + m_2}$$

$$\frac{KE_1}{KE_2} = \frac{m_1 + m_2}{m_1}$$

e)

$$\Delta y = v_0 t - \frac{1}{2}gt^2$$

$$-L = -\frac{1}{2}gt^2$$

$$t = \sqrt{\frac{2L}{g}}$$

$$\Delta x = L + v_2 t = L + \frac{m_1}{m_1 + m_2} \sqrt{2gL} \sqrt{\frac{2L}{g}} = L + \frac{2m_1 L}{m_1 + m_2}$$

## Mech 2.

a)

$$\Delta y = v_0 - \frac{1}{2}gt^2$$

$$-D = -\frac{1}{2}gt^2$$

$$a = \frac{2D}{t^2}$$

- b) i. D and  $t^2$ . Slope of graph is  $a/2$
- ii. Plot D with respect to  $t^2$ , draw the best-fit line.
- iii.  $2.08 \text{ m/s}^2$

c)

$$\sum F_y = ma$$

$$T - mg = -ma$$

$$T = mg - ma$$

$$\tau = r \times F = I\alpha$$

$$RT = I \frac{a}{R}$$

$$I = \frac{R^2 T}{a} = \frac{(mg - ma)R^2}{a}$$

- d) Friction between string and pulley.

## Mech 3.

- a) Parallel Axis Theorem:

$$I_d = I_{CM} + md^2$$

$$I = \frac{ML^2}{12} + M\left(\frac{L}{2} - \frac{L}{3}\right)^2 = \frac{ML^2}{9}$$

b)

$$\tau = r \times F = \frac{L}{6} Mg \sin(90 - \theta)$$

$$W = \int \tau \cdot d\theta = \frac{L}{6} Mg \int_0^{90} \sin(90 - \theta) \cdot d\theta = \frac{MgL}{6}$$

$$W = KE$$

$$\frac{MgL}{6} = \frac{1}{2} I \omega^2$$

$$\frac{MgL}{6} = \frac{1}{2} \frac{ML^2}{9} \omega^2$$

$$\omega = \sqrt{\frac{3g}{L}}$$

$$v = r\omega = \frac{2L}{3} \sqrt{\frac{3g}{L}} = \frac{2}{3} \sqrt{3gL}$$

c) If  $\phi$  is small:

$$\tau = r \times F = \frac{L}{6} Mg \sin(90 - \theta) = \frac{MgL \sin(\phi)}{6} = I\alpha$$

$$\alpha = \frac{MgL \sin(\phi)}{6I} = \frac{MgL \sin(\phi)}{6} \frac{9}{ML^2} = \frac{3g}{2L} \sin(\phi) \approx \frac{3g}{2L} \phi$$

$$\frac{d^2\phi}{dt^2} = \frac{3g}{2L} \phi$$

$$T = 2\pi \sqrt{\frac{2L}{3g}}$$